

# Surface interpolation with local control by linear blending

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## Abstract

The purpose of this paper is to introduce an interactive surface interpolation method by spline surfaces, which is a generalization of the method presented in [2]. The technique is based on linear blending and works for a large class of surfaces including bicubic Bézier, B-spline, NURBS surfaces and the recently developed trigonometric surfaces as well. The interpolating surface can be interactively modified by control points, meanwhile the interpolation property is preserved.

*Keywords:* interpolation, spline surface, linear blending

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## 1. Introduction

Interpolation of an ordered set of points is one of the most widely used methods in curve and surface modeling practice, hence there is a vast number of papers and book chapters dealing with this topic (cf. the books [6, 15] and references therein). Designers generally prefer splines, where most of the methods work globally. Even in the case of B-spline or NURBS surfaces, which are standard description methods in geometric design and have local control properties, the process of finding control points of an interpolating surface is global and the resulted surface cannot be locally controlled (see e.g. [1, 10, 13, 7]). To overcome this problem some methods have been developed by means of which the shape of the interpolating curve or surface can be adjusted by numerical techniques (see e.g. [8, 9, 16]). Shape parameters and other numerical techniques, however, do not provide intuitive shape control methods such as control point repositioning in approximation. Moreover, in these global methods a large system of equations has to be solved at a relatively high

computational cost. Especially, for large set of data points, local methods have the advantage of solving smaller systems, since the computation of each curve segment is based on only a subset of data. Unfortunately, these local methods typically attain only  $C^1$  continuity [11].

In the last couple of years a new local method has been developed for some types of spline curves and surfaces that requires only local computation and yields  $C^2$  continuous spline curves. This technique - which is based on linear blending - has been implemented for NURBS in [17], for B-spline curve in [18] and for trigonometric C-B-spline curve in [14]. In this method the shape of the interpolating curve can also be adjusted numerically by some shape parameters.

In [2] the authors generalized the linear blending interpolation method for a large class of curves. The present contribution is the further generalization of the linear blending curve concept for surfaces. Since designers generally prefer geometric entities instead of numerical values, we provide intuitive, control point based modification of the interpolating surface. We let the designer alter the shape of the surface similarly to the approximating surfaces, meanwhile the interpolation property is continuously preserved.

## 2. Linear blending surfaces

At first we describe a surface generating method which we will call linear blending. Consider the points  $\mathbf{p}_{k,l}$ , ( $k = 0, \dots, n; l = 0, \dots, m$ ) and the piecewisely defined surface

$$\mathbf{b}(u, v) = \sum_{k=-1}^{n+1} \sum_{l=-1}^{m+1} F_k(u) G_l(v) \mathbf{p}_{kl}, \quad u \in [u_0, u_n], v \in [v_0, v_m], \quad (2.1)$$

where  $\mathbf{p}_{kl}$  are called control points (they form the control net consisting of quadrilateral "faces"),  $F_k(u)$  and  $G_l(v)$  are basis functions of some space (not necessarily of the same). The number of faces must be equal to the number of patches. Thus, in case of open surfaces one has to define artificial control points, e.g. by doubling the control points on the boundary of the control net. The only restriction is that each patch of the surface has to be defined by 16 ( $4 \times 4$ ) neighboring control points, that is patches of this surface can be written as

$$\mathbf{b}_{i,j}(u, v) = \sum_{k=i-1}^{i+2} \sum_{l=j-1}^{j+2} F_k(u) G_l(v) \mathbf{p}_{kl}, \quad u \in [u_i, u_{i+1}], v \in [v_j, v_{j+1}]$$

$$i = 0, \dots, n-1, j = 0, \dots, m-1$$

where the values  $u_i, v_j$  are called knots.

Now, consider the  $(i, j)$ th face of the control net determined by the control points  $\mathbf{p}_{i,j}, \mathbf{p}_{i,j+1}, \mathbf{p}_{i+1,j}, \mathbf{p}_{i+1,j+1}$  and interpolate this quadrilateral with the double ruled surface that we obtain from the four corner points by bilinear combination

with some functions  $f(u)$  and  $g(v)$  in the form

$$\mathbf{h}_{i,j}(u, v) = [(1 - f(u)) f(u)] \begin{bmatrix} \mathbf{p}_{i,j} & \mathbf{p}_{i,j+1} \\ \mathbf{p}_{i+1,j} & \mathbf{p}_{i+1,j+1} \end{bmatrix} \begin{bmatrix} (1 - g(v)) \\ g(v) \end{bmatrix},$$

$$u \in [u_i, u_{i+1}], v \in [v_j, v_{j+1}].$$

If the four points are coplanar this surface degenerates to a quadrilateral region in their plane, otherwise it is a patch of a hyperbolic paraboloid (saddle).

For the sake of interpolation, functions  $f(u), g(v)$  have to fulfill conditions

$$f(u_i) = g(v_j) = 0, \quad f(u_{i+1}) = g(v_{j+1}) = 1. \quad (2.2)$$

Linearly blending the patches  $\mathbf{b}_{i,j}(u, v)$  with the corresponding double ruled patches  $\mathbf{h}_{i,j}(u, v)$  we obtain the linear blending surface consisting of the patches

$$\mathbf{c}_{i,j}(u, v, \alpha) = (1 - \alpha)\mathbf{b}_{i,j}(u) + \alpha\mathbf{h}_{i,j}(u),$$

where  $\alpha$  is a global shape parameter of the surface.

To achieve more flexibility in shape modification, the shape parameter  $\alpha$  can also be the function of  $u$  and  $v$ . A natural way is to define them piecewisely by local shape parameters  $\alpha_{i,j}^*$  associated to each point  $\mathbf{p}_{i,j}$ , and to use the same blending functions  $f(u)$  and  $g(v)$  like for the surface  $\mathbf{h}_{i,j}(u, v)$ , i.e.,

$$\alpha_{i,j}(u, v) = [(1 - f(u)) f(u)] \begin{bmatrix} \alpha_{i,j}^* & \alpha_{i,j+1}^* \\ \alpha_{i+1,j}^* & \alpha_{i+1,j+1}^* \end{bmatrix} \begin{bmatrix} (1 - g(v)) \\ g(v) \end{bmatrix}.$$

In this way each patch of the linear blending surface will have four local shape parameters (these parameters initially can be defined to be equal to 1 and will be modified in an interactive way)

$$\mathbf{c}_{i,j}(u, v, \alpha_{i,j}^*, \alpha_{i,j+1}^*, \alpha_{i+1,j}^*, \alpha_{i+1,j+1}^*) = (1 - \alpha_{i,j}(u, v))\mathbf{b}_{i,j}(u, v) + \alpha_{i,j}(u, v)\mathbf{h}_{i,j}(u, v). \quad (2.3)$$

In order to obtain  $C^r (r > 0)$  continuity at joints of consecutive patches, functions  $f(u), g(v)$  have to satisfy the conditions

$$\begin{aligned} f^{(k)}(u_i) = f^{(k)}(u_{i+1}) = 0 & \quad 1 \leq k \leq r, \quad j = 0, \dots, n-1 \\ g^{(k)}(v_j) = g^{(k)}(v_{j+1}) = 0 & \quad 1 \leq k \leq r, \quad j = 0, \dots, m-1 \end{aligned} \quad (2.4)$$

Beside these conditions, the choice of these functions highly depends on the base surface  $\mathbf{b}(u, v)$ , more precisely the type of its basis functions  $F_k(u), G_l(v)$ . The possible choice and generalizations of these functions can be found in [2].

### 3. Interpolation by linear blending surfaces

Now, we generalize the idea of curve interpolation by linear blending described in [17] for surfaces, and we modify the linear blending method defined above to interpolate a given grid of points. Surface patch  $\mathbf{c}_{i,j}(u, v, \alpha_{i,j}^*, \alpha_{i,j+1}^*, \alpha_{i+1,j}^*, \alpha_{i+1,j+1}^*)$

is "between" the patches  $\mathbf{b}_{i,j}(u, v)$  and  $\mathbf{h}_{i,j}(u, v)$ , that is the patch approximates the given points  $\mathbf{p}_{i,j}, \mathbf{p}_{i,j+1}, \mathbf{p}_{i+1,j}, \mathbf{p}_{i+1,j+1}$ . Note, that the method works in that cases as well when the double ruled surface is determined by any four points. We are going to specify such four corner points for the double ruled surface  $\mathbf{h}_{i,j}(u, v)$  that the resulted blending patch  $\mathbf{c}_{i,j}$  will interpolate the given points.

Let the points  $\mathbf{p}_{i,j}$ , associated parameter values  $(u_i, v_j)$  and shape parameters  $\alpha_{i,j}^*$ , ( $i = 0, \dots, n, j = 0, \dots, m$ ) be given. The problem is to find a linear blending patch that has the given shape parameters  $\alpha_{i,j}^*$  and interpolates the given points  $\mathbf{p}_{i,j}$  at the given parameter values  $(u_i, v_j)$ .

Let us consider the approximating patch defined by the given points as control points

$$\mathbf{b}_{i,j}(u, v) = \sum_{k=i-1}^{i+2} \sum_{l=j-1}^{j+2} F_k(u)G_l(v) \mathbf{p}_{kl}, \quad u \in [u_i, u_{i+1}], v \in [v_j, v_{j+1}],$$

and the double ruled patch

$$\mathbf{h}_{i,j}(u, v) = \left[ (1 - f(u)) \ f(u) \right] \begin{bmatrix} \mathbf{v}_{i,j} & \mathbf{v}_{i,j+1} \\ \mathbf{v}_{i+1,j} & \mathbf{v}_{i+1,j+1} \end{bmatrix} \begin{bmatrix} (1 - g(v)) \\ g(v) \end{bmatrix},$$

$$u \in [u_i, u_{i+1}], v \in [v_j, v_{j+1}]$$

where the points  $\mathbf{v}_{i,j}$  are unknown. Using the interpolation assumptions

$$\begin{aligned} \mathbf{c}_{i,j}(u_i, v_j, \alpha_{i,j}^*, \alpha_{i,j+1}^*, \alpha_{i+1,j}^*, \alpha_{i+1,j+1}^*) &= \mathbf{p}_{i,j} \\ \mathbf{c}_{i,j}(u_i, v_{j+1}, \alpha_{i,j}^*, \alpha_{i,j+1}^*, \alpha_{i+1,j}^*, \alpha_{i+1,j+1}^*) &= \mathbf{p}_{i,j+1} \\ \mathbf{c}_{i,j}(u_{i+1}, v_j, \alpha_{i,j}^*, \alpha_{i,j+1}^*, \alpha_{i+1,j}^*, \alpha_{i+1,j+1}^*) &= \mathbf{p}_{i+1,j} \\ \mathbf{c}_{i,j}(u_{i+1}, v_{j+1}, \alpha_{i,j}^*, \alpha_{i,j+1}^*, \alpha_{i+1,j}^*, \alpha_{i+1,j+1}^*) &= \mathbf{p}_{i+1,j+1} \end{aligned} \quad (3.1)$$

we obtain

$$\begin{aligned} \mathbf{v}_{i,j} &= \mathbf{p}_{i,j} + \frac{1 - \alpha_{i,j}^*}{\alpha_{i,j}^*} (\mathbf{p}_{i,j} - \mathbf{b}_{i,j}(u_i, v_j)) \\ \mathbf{v}_{i,j+1} &= \mathbf{p}_{i,j+1} + \frac{1 - \alpha_{i,j+1}^*}{\alpha_{i,j+1}^*} (\mathbf{p}_{i,j+1} - \mathbf{b}_{i,j}(u_i, v_{j+1})) \\ \mathbf{v}_{i+1,j} &= \mathbf{p}_{i+1,j} + \frac{1 - \alpha_{i+1,j}^*}{\alpha_{i+1,j}^*} (\mathbf{p}_{i+1,j} - \mathbf{b}_{i,j}(u_{i+1}, v_j)) \\ \mathbf{v}_{i+1,j+1} &= \mathbf{p}_{i+1,j+1} + \frac{1 - \alpha_{i+1,j+1}^*}{\alpha_{i+1,j+1}^*} (\mathbf{p}_{i+1,j+1} - \mathbf{b}_{i,j}(u_{i+1}, v_{j+1})). \end{aligned} \quad (3.2)$$

By means of these points, the corresponding linear blending patches will interpolate the given points at the given parameter values (see Fig.1).

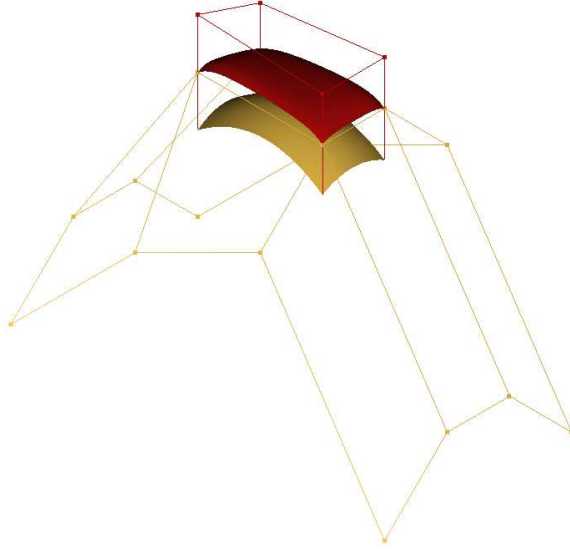


Figure 1: The original base surface (below) and the interpolating linear blending surface with the calculated four control points.

## 4. Interactive shape modification

Points  $\mathbf{v}_{i,j}$  depend on three parameters: the corresponding parameter values  $u_i, v_j$  and the local shape parameter  $\alpha_{i,j}^*$ . Instead of manipulating these values numerically, calculating the points  $\mathbf{v}_{i,j}$  and finally the interpolating surface patch  $\mathbf{c}_{i,j}(u, v, \alpha_{i,j}^*, \alpha_{i,j+1}^*, \alpha_{i+1,j}^*, \alpha_{i+1,j+1}^*)$ , we intend to develop an interactive shape modification tool. In this tool points  $\mathbf{v}_{i,j}$  shall be used analogously to the control points of an approximating surface, meanwhile the interpolating property of the surface is preserved. Although, these points are not "real" control points of the surface, the geometric effect of dragging these points is quite similar to the effect of control point repositioning.

When the position of the point  $\mathbf{v}_{i,j}$  is modified, we have to recalculate the actual values of parameters  $u_i, v_j$  and  $\alpha_{i,j}^*$  to preserve the interpolation. This problem leads us to the following questions: what happens to the surface (and especially to the point  $\mathbf{v}_{i,j}$ ) if one of these parameters is changed? What are the possible positions of the point  $\mathbf{v}_{i,j}$ ?

At first let us fix the parameters  $u_i, v_j$  and alter the shape parameter  $\alpha_{i,j}^*$ . It is obvious from Eq. (3.2) that preserving the interpolation property the point  $\mathbf{v}_{i,j}$  will move along a straight line connecting the given point  $\mathbf{p}_{i,j}$  and the point  $\mathbf{b}_{i,j}(u_i, v_j)$  of the original surface patch.

Now, consider the case when the shape parameter  $\alpha_{i,j}^*$  is fixed and the parameters  $u_i, v_j$  are altered. By Eqs. (3.1) the surface interpolates the point  $\mathbf{p}_{i,j}$

at parameters  $(u_i, v_j)$ , which may vary between  $u_{i-1}, u_{i+1}$  and  $v_{j-1}, v_{j+1}$ , respectively. These values, however also serve as knot values of the original base surface (2.1). Therefore, the alteration of these parameters changes the shape of the original surface patch  $\mathbf{b}_{i,j}(u, v)$  as well. The geometric description of the effect of knot alteration is far from being trivial. For B-spline and NURBS surfaces it has been described in detail in [3], [4], [12] and [5]. Using the results of these studies we can conclude that the point  $\mathbf{b}_{i,j}(u_i, v_j)$  of the base surface will move along a well-defined surface patch

$$\mathbf{e}(u_i, v_j) = \mathbf{b}_{i,j}(u_i, v_j) \quad u_i \in [u_{i-1}, u_{i+1}], v_j \in [v_{j-1}, v_{j+1}]. \quad (4.1)$$

E.g., in case of a B-spline surface of degree  $(k, l)$ , the surface  $\mathbf{e}(u_i, v_j)$  is a B-spline surface patch of degree  $(k-1, l-1)$ , defined by the same control points and knot values (except the knots  $u_i$  and  $v_j$ ) as the original surface [3].

By means of Eqs. (3.2) it is easy to see that altering the parameters  $u_i, v_j$  the point  $\mathbf{v}_{i,j}$  will move along a surface that can be obtained by a central similarity from surface (4.1), where the center of similitude is the given point  $\mathbf{p}_{i,j}$  and the ratio is  $(1 - \alpha_{i,j}^*) / \alpha_{i,j}^*$ .

Summarizing the above results one can see that the permissible positions of  $\mathbf{v}_{i,j}$  is a volume bounded by a cone-like surface the apex of which is the given point  $\mathbf{p}_{i,j}$  and its base is composed of the four boundary curves of the envelope surface (4.1) (see Fig.2).



Figure 2: The original surface (below) and the interpolating linear blending surface. The permissible positions of the upmost control point is shown by a volume bounded by a cone-like surface.

For each actual position of  $\mathbf{v}_{i,j}$  within this region one has to recalculate the parameters  $u_i, v_j$  and  $\alpha_{i,j}^*$ , and (by fixing the rest of the shape parameters) substitute them into  $\mathbf{c}_{i,j}(u, v, \alpha_{i,j}^*, \alpha_{i,j+1}^*, \alpha_{i+1,j}^*, \alpha_{i+1,j+1}^*)$  in order to obtain the interpolating surface.

## 5. Conclusions

An easy-to-compute interpolation method is presented in this paper, based on linear blending of a base surface and a computed control mesh. The resulted surface can interactively be modified by the points of this control mesh, meanwhile the interpolation property continuously holds. The method works for a large class of surfaces, including all the standard surface types (Bézier, B-spline, NURBS, C-B-spline, etc.) of computer aided geometric design.

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